



Call for Papers

14th International Symposium on Stabilization, Safety, and Security of Distributed Systems (SSS 2012)



October 1-4, 2012
TORONTO, Canada

<http://www.cs.uwaterloo.ca/sss2012/>



General Chair

Sukumar Ghosh *U Iowa, USA*

Program Co-Chairs

Andrea Richa *ASU, USA*

Christian Scheideler *U Paderborn, Germany*

Program Vice Chairs

Self-Stabilization

Sylvie Delaet *LRI / U Paris-Sud 11, France*

M. G. Potop-Butucaru *U Paris 6, France*

Ad-Hoc and Sensor Networks

Murat Demirbas *SUNY Buffalo, USA*

Fault-Tolerant and Dependable Systems

Rida Bazzi *ASU, USA*

Safety and Security

Felix Freiling *Friedrich-Alexander U, Germany*

Cloud Computing

Mohamed Gouda *U Texas at Austin, USA*

Formal Methods

Borzoo Bonakdarpour *U Waterloo, Canada*

Social Networks

Sonja Buchegger *KTH, Sweden*

Thorsten Strufe *TU Darmstadt, Germany*

Peer-to-Peer, Self-Organizing and

Autonomic Systems

Fabian Kuhn *U Lugano (CH) & U Freiburg (D)*

Christian Schindelhauer *U Freiburg, Germany*

Local Arrangements Chairs

Borzoo Bonakdarpour *U Waterloo, Canada*

Bernard Wong *U Waterloo, Canada*

Publicity Chair

Stefan Schmid *TU Berlin & T-Labs, Germany*

Scope

The SSS symposium is a prestigious international forum for researchers and practitioners in the design and development of fault-tolerant distributed systems with self-* properties, such as self-stabilizing, self-configuring, self-organizing, self-managing, self-repairing, self-healing, self-optimizing, self-adaptive, and self-protecting systems. Research in distributed systems is now at a crucial point in its evolution, marked by the importance of dynamic systems such as cloud networks, social networks, peer-to-peer networks, large-scale wireless sensor networks, mobile ad hoc networks, robotic networks, etc., and many new applications such as grid and web services, banking and e-commerce, e-health and robotics, aerospace and avionics, automotive, industrial process control, etc. have joined the traditional applications of distributed systems.

The conference provides a wide spectrum of topics, covered in the following tracks:

- Self-Stabilization
- Ad-Hoc and Sensor Networks
- Fault-Tolerance and Dependable Systems
- Safety and Security
- Cloud Computing
- Formal Methods
- Social Networks
- Peer-to-Peer, Self-Organizing and Autonomic Systems

Paper Submission

Papers must be submitted in PDF format and be prepared using the LNCS style. Detailed instructions for submitting papers will be available later. Two types of papers can be submitted: **Regular Papers** and **Brief Announcements**. Submissions for regular papers should be no longer than **15 pages** (including the title, authors, abstract, figures, and references) in **LNCS style**; a submission may have an appendix of at most two pages beyond the 15 page limit. Brief announcements are restricted to two pages using the LNCS style, with no appendix. Submissions deviating from these guidelines will be rejected without consideration of their merits.

If requested by the authors on the submission system, a regular submission that is not selected for a regular presentation will also be considered for a brief announcement. Such a request will not affect consideration of the paper for a regular paper.

A paper submitted at this forum is expected to be original research not previously published. A contribution can be submitted to one track only and may not be concurrently submitted to another conference, workshop, or journal.

Publication

The proceedings of the conference will be published in the **Springer Verlag Lecture Notes in Computer Science (LNCS)** series.

Best Paper and Best Student Awards

The program committee will select two papers for best paper and best student paper awards. A paper is eligible for the best student paper award if at least one of its authors is a full-time student at the time of submission, and if the student made a major contribution. Marking an appropriate box in the submission system must indicate this.

Important Dates

- **Abstract Submission: April 16, 2012**
- **Paper Submission: April 23, 2012**
- **Notification: June 6, 2012**